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## Ditec LCU4OH Himaling

Control panel installation manual for automations with one or two 24 V motors =-


## Contents

|  | Subject | Page |
| :---: | :---: | :---: |
| 1. | General safety precautions | 3 |
| 1.1 | Safety functions | 4 |
| 2. | EC Declaration of Conformity | 4 |
| 3. | Technical specifications | 4 |
| 3.1 | Applications | 4 |
| 4. | Installation and electrical connections | 5 |
| 4.1 | Maintenance | 7 |
| 4.2 | Standard installation | 7 |
| 4.3 | Standard installation diagram | 8 |
| 5. | Programming | 9 |
| 5.1 | Switching the display ON and OFF | 9 |
| 5.2 | Navigation keys | 9 |
| 5.3 | Menu map | 10 |
| 6. | Quick start-up sequences | 12 |
| 6.1 | Selection of automation type | 12 |
| 6.2 | Configuration of the number of gate wings | 12 |
| 6.3 | Enabling the configurations | 12 |
| 6.4 | Adding remote controls | 12 |
| 6.5 | Configuration of the limit switches | 13 |
| 6.6 | Configuration of the safety devices | 13 |
| 7. | Application examples | 14 |
| 7.1 | Automations with two swinging gates | 14 |
| 7.2 | Automations with one swinging gate wing | 14 |
| 7.3 | Up-and-over doors with two parallel motors | 15 |
| 8. | Commands | 16 |
| 8.1 | Inserting plug-in boards (AUX) | 17 |
| 8.2 | SOFA1-SOFA2 or GOPAVRS self-controlled safety edge | 17 |
| 9. | Outputs and accessories | 18 |
| 10. | Selections | 19 |
| 11. | Adjustments | 20 |
| 11.1 | Main menu | 20 |
| 11.2 | Second level menu - AT (Automatic Configurations) | 21 |
| 11.2.1 | Selecting the type of automation AT $\rightarrow$ AS and specific default settings | 22 |
| 11.3 | Second level menu - BC (Basic Configurations) | 23 |
| 11.3.1 | Additional BC level parameters that can be configured (available with AT $\rightarrow$ AA enabled) | 23 |
| 11.4 | Second level menu - BA (Basic Adjustment) | 24 |
| 11.4.1 | Additional BA level parameters that can be configured (available with AT $\rightarrow$ AA enabled) | 26 |
| 11.5 | Second level menu - RO (Radio Operations) | 28 |
| 11.5.1 | Additional RO level parameters that can be configured (available with AT $\rightarrow$ AA enabled) | 29 |
| 11.6 | Second level menu - SF (Special Functions) | 30 |
| 11.6.1 | Additional SF level parameters that can be configured lavailable with AT $\rightarrow$ AA enabled) | 31 |
| 11.7 | Second level menu - CC (Cycle Counter) | 32 |
| 11.7.1 | Additional CC level parameters that can be configured (available with AT $\rightarrow$ AA enabled) | 33 |
| 11.8 | Second level menu - EM (Energy Management) | 33 |
| 11.8.1 | Additional EM level parameters that can be configured (available with AT $\rightarrow$ AA enabled) | 34 |
| 11.9 | Second level menu - AP (Advanced Parameters) | 34 |
| 11.9.1 | Additional AP level parameters that can be configured (available with AT $\rightarrow$ AA enabled) | 36 |
| 12. | Diagnostics | 38 |
| 12.1 | Data Logging integrated in the board | 38 |
| 12.1.1 | Alarm counter | 38 |
| 12.1.2 | Alarm log | 38 |
| 12.1.3 | Exporting information on the microSD | 39 |
| 12.2 | Extended data logging on microSD | 39 |
| 13. | Signals visualised on the display | 40 |
| 13.1 | Display of automation status | 40 |
| 13.2 | Display of safety devices and commands | 40 |
| 13.3 | Visualisation of alarms and faults | 42 |
| 14. | Troubleshooting | 45 |
| Key |  |  |
|  | This symbol indicates instructions or notes regarding safety, to which special attention must be paid |  |
| This symbol indicates useful information for the correct functioning of the product. |  |  |
|  | Factory settings |  |

## 1. General safety precautions



Failure to observe the information given in this manual may lead to personal injury or damage to the equipment. Keep these instructions for future reference

This installation manual is intended for qualified personnel only. Installation, electrical connections and adjustments must be performed in accordance with Good Working Methods and in compliance with the present standards.
This product must only be used for the specific purpose for which it was designed. Any other use is to be considered improper and therefore dangerous. The manufacturer cannot be held responsible for any damage caused by improper, incorrect or unreasonable use.
Read the instructions carefully before installing the product. Incorrect installation could be dangerous.

$\approx$The packaging materials (plastic, polystyrene, etc.) should not be discarded in the environment or left within reach of children, as they are a potential source of danger.
Before installing the product, make sure it is in perfect condition.
Do not install the product in explosive areas and atmospheres: the presence of inflammable gas or fumes represents a serious safety hazard.
The safety devices (photocells, safety edges, emergency stops, etc.) must be installed taking into account the applicable laws and directives, Good Working Methods, installation premises, system operating logic and the forces developed by the automation. Before connecting the power supply, make sure the plate data correspond to those of the mains power supply. An omnipolar disconnection switch with a contact opening distance of at least 3 mm must be fitted on the mains supply.
Check that there is an adequate residual current circuit breaker and a suitable overcurrent cut-out upstream of the electrical installation in accordance with Good Working Methods and with the laws in force.
When requested, connect the automation to an effective earthing system that complies with current safety standards.


During installation, maintenance and repair operations, cut off the power supply before opening the cover to access the electrical parts.
The electronic parts must be handled using earthed antistatic conductive arms. The manufacturer of the motorisation device declines all responsibility if component parts not compatible with safe and correct operation are fitted.
Only use original spare parts when repairing or replacing products.

### 1.1 Safety functions

The Ditec LCU40H control panel has the following safety functions:

- obstacle recognition with force limiting;

The maximum response time of the safety functions is 0.5 s . The reaction time to a faulty safety function is 0.5 s .
The safety functions comply with the standards and performance level indicated below:

$$
\begin{aligned}
& \text { EN ISO 13849-1:2015 Category } 2 \text { PL=c } \\
& \text { EN ISO 13849-2:2012 }
\end{aligned}
$$

The safety function cannot be bypassed either temporarily or automatically. Fault exclusion has not been applied.

## 2. EC Declaration of Conformity

ASSA ABLOY Entrance Systems AB declares that the Ditec LCU40H control panel complies with the fundamental requisites and other relevant requirements laid down by the following EC directives:
EMC Directive 2014/30/EU;
Low Voltage Directive 2014/35/EU;
RED Directive 2014/53/EU.
Landskrona, 18-05-2021

3. Technical specifications

|  | LCU4OH | LCU40HJ |
| :---: | :---: | :---: |
| Power supply | $230 \mathrm{~V} \sim 50 / 60 \mathrm{~Hz}$ | $120 \mathrm{~V} \sim 50 / 60 \mathrm{~Hz}$ |
| Power absorption | 0,6A | 1,2A |
| Fuse | F2A | 4A |
| Motor output | $24 \mathrm{~V}=12 \mathrm{~A}$ max (X |  |
| Permanent power supply to accessories 0-30 | $24 \mathrm{~V}=0,15 \mathrm{~A}$ |  |
| Power supply to accessories 0-1 lin any case, the total of accessories 0-30 and 0-1 must not exceed 0.5A). | $24 \mathrm{~V}=0.5 \mathrm{~A}$ contin |  |
| Ambient temperature | $-20^{\circ} \mathrm{C}-+55^{\circ} \mathrm{C}$ |  |
| Storable radio codes | 100 / 200 see R | $\rightarrow$ 20/10 (paragraph 11.6) |
| Radio frequency | $433,92 \mathrm{MHz}$ |  |
| Degree of protection of the container | IP55 |  |
| Product size | $238 \times 357 \times 120$ |  |
| Operating cycles | Refer to the char | of the actuator used. |
| NOTE: the given operating and performance features can only be guaranteed with the use of DITEC accessories and safety devices. |  |  |

3.1 Applications


## 4. Installation and electrical connections

- Perforate the relevant points in the bottom part of the box (Fig. 4.1).
- Fix the control panel firmly in place. You are advised to use convex head screws (max head $\emptyset 10 \mathrm{~mm}$ ) with a cross imprint (the centre distance for the holes is shown in Fig. 4.2).
- Insert the cable glands and corrugated tubes from the lower side of the container.
- Before connecting the power supply, make sure the plate data correspond to those of the mains power supply.
- An omnipolar disconnection switch with a contact opening distance of at least 3 mm must be fitted on the mains supply.
- Check there is an adequate residual current circuit breaker and overcurrent cut-out upstream of the electrical system.
- For the power supply, use a H05RN-F 3G1.5 type electric cable. Connect it to the terminals $L$ (brown), N (blue), $\triangleq$ (yellow/green) inside the automation (Fig. 4.3, page 6).
NOTE: the maximum permitted wire section is AWG14 ( $2 \mathrm{~mm}^{2}$ ).
- Unsheathe the part of the power supply cable in line with the terminal, and use a cable fastener to hold it in place [A].
- In order to comply with the essential requisites of the Standards in force, reclose the cover once the wires have been connected to the terminal.

The connections to the mains power supply and to any possible low voltage wires (230V) in the section outside the control panel must be made on an independent channel separated from the connections to the command and safety devices (SELV= Safety Extra Low Voltage). The corrugated tubes must enter the control panel by a few centimetres via the holes on the base box.

- Make sure there are no sharp edges that may damage the cables.
- Make sure the mains power wires (230V) and the accessory wires (24V) are separated.
- The cables must have dual insulation, be sheathed near the relative connection terminals, and be held in place with ties [B] (not supplied).
- If necessary, fit the clip hinges on the bottom of the box and on the cover (left or right side, as preferred) (Fig. 4.4, page 6).
After making the adjustments and settings, fix the cover in place with the screws supplied (Fig. 4.5 , page 6).

Fig. 4.1


Fig. 4.2


Fig. 4.3



Fig. 4.5


### 4.1 Maintenance

The control panel needs no special maintenance.
Make regular checks to ensure the good condition of the box seals and the electrical connections.

### 4.2 Standard installation



| Ref. | Description | Cable |
| :---: | :---: | :---: |
| 1 | Transmitter | 1 |
| 2 | Flashing light | $2 \times 1 \mathrm{~mm}^{2}$ |
|  | Antenna (integrated in the flashing light) | coaxial $50 \Omega$ |
| 3 | Key selector switch | $4 \times 0.5 \mathrm{~mm}^{2}$ |
|  | Digital combination wireless keypad | 1 |
| 4 | Actuator | $2 \times 1.5 \mathrm{~mm}^{2}$ |
|  | Actuator with limit switch | $3 \times 1.5 \mathrm{~mm}^{2}$ |
| 5 | Photocells | $4 \times 0.5 \mathrm{~mm}^{2}$ |
| 6 | Control panel | $3 \mathrm{G} \times 1.5 \mathrm{~mm}^{2}$ |
| A | Connect the power supply to a type-approved omnipolar switch, with a contact opening distance of at least 3 mm (not supplied). <br> Connection to the mains must be via an independent channel, separated from the connections to the command and safety devices. |  |

4.3 Standard installation diagram


## 5. Programming

### 5.1 Switching the display ON and OFF

The procedure to switch on the display is as follows:

- press the ENTER key

- the display functioning check starts

- the first level menu is displayed


The procedure to switch off the display is as follows:

- press the ESC key $\boxed{\boxed{E E S C}}$

NOTE: the display switches off automatically after 60s of inactivity.

### 5.2 Navigation keys

- The simultaneous pressing of the $\uparrow$ and ENTER keys produces an opening command.

- The simultaneous pressing of the $\downarrow$ and ENTER keys produces a closing command.

- The simultaneous pressing of the $\uparrow$ and $\downarrow$ keys produces a POWER RESET command (power supply interruption and automation restart).

- Keep the UP $\uparrow$ or DOWN $\downarrow$ key pressed to begin fast menu scrolling.
- In some menus, the parameter measurement unit can be viewed by pressing the ENTER key once the value has been displayed.
Example: setting of 10 seconds for parameter OB.






## *

Additional configurable parameters available with AT $\rightarrow$ AA is enabled.

## 6. Quick start-up sequences

### 6.1 Selection of automation type

Example of PWR25 automation selection
Set

Example of PWR35 automation selection
Set

NOTE: if no automation is selected (alarm M active) using the can access the values of parameter $\wp^{\circ} \bar{\jmath}$ directly.

### 6.2 Configuration of the number of gate wings

Configuration example for a single gate wing
Set


### 6.3 Enabling the configurations

Step-by-step mode without automatic closure (residential use)


Step-by-step mode with automatic closure 1 min (residential use) [standard settings]


Opening mode with automatic closure 1 min (condominium use)



### 6.5 Configuration of the limit switches

## Example 1 - Door wing stops against mechanical end stops (standard setting)

Set


Example 2 - Door wing stops against limit switches
Set


With these settings, if an obstacle is detected while the gate wing is opening, it stops with a disengagement operation; during closure, the gate wing reopens).

Example 3 - Door wing stops against mechanical end stops and reverses motion if an obstacle is detected
Set


With these settings, the gate wing stops against its respective mechanical closing end stop and the opening limit switch.
If an obstacle is detected during the opening and before the activation of the stop limit switch, the gate wing stops with a disengagement operation.
If an obstacle is detected during closure and before the activation of the proximity limit switch, the gate wing reopens; once the proximity limit switch has been activated, the gate wing stops against the obstacle.

### 6.6 Configuration of the safety devices

Example 1 - Configuration of the photocells connected to terminals 1-8 and 1-6 [standard settings] Set


Example 2 - Configuration of the safety edge with safety test simultaneously connected to terminals 1-6 and 1-8
Set


## 7. Application examples

WARNING: Ensure that the forces exerted by the door wings are compliant with EN12453-EN12445 regulations.

### 7.1 Automations with two swinging gates



When the Ditec LCU40H control panel is used in applications for automations with two overlapping swinging gate wings, the following connections can be made:

(Fig. 7.1) Installation with mechanical end stops for opening and closure, and without the use of electric limit switches.
(Fig. 7.2) Installation with mechanical end stop for closure, and with the use of electric limit switches (stop during opening and proximity during closure).

### 7.2 Automations with one swinging gate wing



When the Ditec LCU40H control panel is used in applications for automations with one swinging gate wing, the following connections can be made:

(Fig. 7.3) Installation with mechanical end stops for opening and closure, and without the use of electric limit switches.
(Fig. 7.4) Installation with mechanical end stop for closure, and with the use of electric limit switches (stop during opening and proximity during closure).

### 7.3 Up-and-over doors with two parallel motors



When the Ditec LCU40H control panel is used in applications for automations with up-and-over doors with two parallel motors, the following connections can be made:

(Fig. 7.5) Installation with mechanical end stops for opening and closure, and without the use of electric limit switches.
[Fig. 7.6] Installation with electric limit switches for deceleration during opening and closure.

[Fig. 7.7] Installation with electric limit switches (stop during opening and closure).
[Fig. 7.8] Installation with electric limit switches (stop during opening and proximity during closure).

## 8．Commands

You are advised to read paragraph 11 for all the details about the possible adjustments．
WARNING：terminal 30 （common positive for commands）has the same functions as terminal 1 ，
 so the commands visible on the display are indicated with 1－5，1－3，1－4，etc．It is different from terminal 1，however，because of the maximum current that can be dispensed and it is also active when the control panel is in standby $E \bar{J} \rightarrow \square \mathrm{~N}$ ．

| Command |  | Function | Description |
| :---: | :---: | :---: | :---: |
| $30-2$ | NO | AUTOMATIC CLOSURE | The permanent closure of the contact enables automatic closure if $A[\rightarrow 1-己$ |
| $30-3$ | NO | OPENING | When selecting $B[\rightarrow 35 \rightarrow 1-]$ ，the closure of the contact activates an opening operation． |
|  |  | STEP－BY－STEP | When selecting $B[\rightarrow 35 \rightarrow 1-5$ ，the closure of the contact activates a sequential opening or closing operation：opening－stop－closing－ope－ ning．The＂opening－stop－closing－opening＂sequence can be changed to＂opening－stop－closing－stop－opening＂by selecting $B[\rightarrow P P$ ． |
| $30-4$ | NO | CLOSURE | The closure of the contact activates a closing operation． |
| $30-5$ | NO | STEP－BY－STEP | When selecting $B[\rightarrow[5 \rightarrow 1-5$ ，the closure of the contact activates a sequential opening or closing operation：opening－stop－closing－ opening． <br> WARNING：if automatic closure is enabled，the duration of the stop can be defined by selecting $B[\rightarrow 55$ ． <br> The＂opening－stop－closing－opening＂sequence can be changed to ＂opening－stop－closing－stop－opening＂by selecting $B[\rightarrow P P$ ． |
|  |  | OPENING | When selecting $B[\rightarrow[5 \rightarrow \mid-]$ ，the closure of the contact activates an opening operation． |
| L 6 | NC | SAFETY STOP | The opening of the safety contact stops and prevents any movement． NOTE：RP $\overline{\mathrm{J} M}$ to set different safety contact functions，see the $\rightarrow$ parameter settings． |
| t 8 | NC | CLOSING SAFETY DE－ VICE | The opening of the safety contact triggers a reversal of the movement （reopening）during the closing operation． <br> When selecting $B[\rightarrow \bar{J} \square \rightarrow \square \mathrm{~N}$ ，the opening of the contact prevents any operation when the automation is idle． <br> When selecting $B[\rightarrow \bar{\zeta} \square \rightarrow \square F$ ，the opening of the contact only prevents closure when the automation is idle． |
|  | NC | CLOSING／ OPENING SAFETY DE－ VICE | The opening of the safety contact stops and prevents any movement． NOTE：operation corresponds to that of contact $1-6$ with RP $\rightarrow 5 \mathrm{M}$ $\rightarrow 05$ ． |
| $30-9$ | NC | STOP | The opening of the safety contact causes the current operation to stop． If AP－R G＝9P ，automatic closure is disabled when contact 30－9 recloses． <br> If RP－RG＝马T，automatic closure remains enabled when contact 30－9 recloses． |
| $30-9$ | NO | ＂OPERATOR PRESENT＂ COMMAND | When selecting $R P \rightarrow R 马 \rightarrow H R$ ，the opening of contact $30-9$ enables the＂operator present＂function： <br> －opening with operator present 30－3 <br> －closure with operator present 30－4 <br> NOTE：any safety devices，automatic closure and plug－in board in the AUX housing are all disabled． |
| $30-20$ | NO | PARTIAL OPENING | The closure of the contact activates a partial opening operation． Once the automation stops，the partial opening control performs the opposite operation to the one performed before the stop． |

$\triangle$
WARNING：make a jumper for all NC contacts if not used，or deactivate them via the relative menu．Terminals with the same number are equal．

### 8.1 Inserting plug-in boards (AUX)

To access the slots for plug-in boards (AUX):

- If you want to insert just one board, cut the control panel cover and remove it as shown in the figure.
- If both slots are needed, remove the cover completely.



### 8.2 SOFA1-SOFA2 or GOPAVRS self-controlled safety edge

| Command |  | Function | Description |
| :---: | :---: | :---: | :---: |
| $\begin{gathered} \text { SOFA1-SOFA2 } \\ \text { GOPAV } \end{gathered}$ |  | SAFETY TEST | Insert the SOFA1-SOFA2 or GOPAVRS device in the slot for plug-in boards AUX1 or AUX2. <br> If the test fails, an alarm message appears on the display. |
| $00000$ |  |  |  |
| $1 \longrightarrow 6$ | NC | SAFETY STOP | When selecting RP $\rightarrow \mathbb{D G} \rightarrow \overline{5} 41$, connect the output contact of the safety device to terminals 1-6 on the control panel lin series with the photocell output contact, if installed). |
| $1 \longrightarrow 8$ | NC | CLOSING SAFE- <br> TY DEVICE | When selecting RP $\rightarrow$ IB $\rightarrow$ 丂 41 , connect the output contact of the safety device to terminals 1-8 on the control panel lin series with the photocell output contact, if installed). |
| $1 \longrightarrow L_{8}^{6}$ | NC | $\begin{gathered} \text { CLOSING/ } \\ \text { OPENING } \\ \text { SAFETY DEVICE } \end{gathered}$ | When selecting RP $\rightarrow$ G日 $\rightarrow \Sigma 41$, connect the output contact of the safety device to terminals 1-6-8 on the control panel lin series with the photocell output contact, if installed). <br>  |

## 9. Outputs and accessories

| Value of |
| :--- | :--- |
| accessories |$\quad$| Power supply to accessories |
| :--- |
| Output for power supply to external accessories. |
| NOTE: the maximum absorption of 0.5 A corresponds to the |
| sum of all terminals 1. |


| Output | Value of accessories | Description |
| :---: | :---: | :---: |
|  | MicroSD | The control panel manages microSD cards for updating the firmware and for diagnostics and configuration storage/recovery via the in commands $\bar{J}^{\circ} F \rightarrow \bar{J}^{\prime} b^{\prime}$ and $\zeta^{\prime} F \rightarrow R[$. <br> NOTE: use a microSD with a maximum capacity no greater than 16 Gb . |
| COM | BIXMR2 | COM - This allows the functioning configurations to be saved using the function ${ }^{\top} \zeta F \rightarrow{ }^{5} \zeta$ '. <br> The saved configurations can be recalled using the function广 $F \rightarrow$ R $[$. |
|  |  | COM - The storage module allows the remote controls to be stored. If the control panel is replaced, the storage module being used can be inserted in the new control panel. <br> WARNING: the storage module must be inserted and removed with the power supply disconnected, and paying attention to the positioning direction. |
| $\begin{aligned} & \text { BAT } \\ & \begin{array}{\|l\|l\|} \hline \square & \square \\ \hline= & - \\ \hline \end{array} \end{aligned}$ | SBU | BAT - Battery-powered operation. <br> The batteries are kept charged when the power supply is on. If the power supply is off, the panel is powered by the batteries until the power is re-establish or until the battery voltage drops below the safety threshold. The panel turns off in the last case. <br> WARNING: the batteries must always be connected to the control panel for charging. Periodically check the efficiency of the batteries. <br> NOTE: the operating temperature of the rechargeable batteries is from $+5^{\circ} \mathrm{C}$ to $+40^{\circ} \mathrm{C}$. For advanced control of battery-powered operation, refer to the menu EM. |

## 10. Jumper setting

| Jumper | Description | OFF | ON |
| :---: | :--- | :--- | :--- |
| JR1 | Display mode selection | Display mode. <br> Only the values and pa- <br> rameters present can be <br> displayed. | Maintenance mode. <br> Only the values and pa- <br> rameters present can be <br> displayed and modified. <br> Activated maintenance <br> mode is indicated by the |
| permanent switching on of |  |  |  |
| the right-hand point on the |  |  |  |
| display. |  |  |  |


| Jumper | Description | $\begin{array}{rr} 1 & 30 \\ \hline & \quad \\ \hline \end{array}$ | $1 \quad 30$ <br> $\bullet \quad . \quad 0$ |
| :---: | :---: | :---: | :---: |
| AUX1 | Selection of power supply - auxiliary board 1 | AUX1 powered from 0-1. | AUX1 powered from 0-30. |
| AUX2 | Selection of power supply - auxiliary board 2 | AUX2 powered from 0-1. | AUX2 powered from 0-30. |

## 11. Adjustments

i
NOTE: depending on the type of automation and control panel, some menus may not be available.

### 11.1 Main menu

| Display | Description |
| :---: | :---: |
|  | AT - Automatic Configurations. <br> The menu allows you to manage the automatic configurations of the control panel. |
|  | BC - Basic Configurations. <br> The menu allows you to display and modify the main settings of the control panel. |
|  | BA - Basic Adjustments. <br> The menu allows you to display and modify the main adjustments of the control panel. NOTE: some settings require at least three operations before they are set correctly. |
|  | RO - Radio Operations. <br> The menu is used to manage the radio functions of the control panel lalarm management, diagnostics enabling, FW updating). |
|  | SF - Special Functions. <br> The menu allows you to set the password and manage the special functions in the control panel. |
|  | CC - Cycles Counter. <br> The menu allows you to display the number of operations carried out by the automation and manage the maintenance interventions. |
| $E M 1$ | EM - Energy Management. <br> The menu allows you to display and modify the energy saving settings and adjustments (Green Mode and battery management). |
|  | AP - Advanced Parameters. <br> The menu allows you to display and modify the advanced settings and adjustments of the control panel (limit switch mode, selection of devices connected to the terminals, disengagement duration adjustments, flashing light adjustments, etc.). <br> NOTE: some settings require at least three operations before they are set correctly. |

From the main menu you can access the second level menu as follows:

- use the and keys to select the required function
- press $\sqrt{\text { Einer }}$ to confirm

After confirming the selection, you access the second level menu.
For each function of the main menu, there are also additional configurations that can be viewed by enabling the $Я$ function (see the following paragraph).

### 11.2Second level menu - AT (Automatic Configurations)

AS - Automation selection
This selection pre-sets the type of motor and a sub-set of parameters
linked to the kinematic mechanism of the automation for a standard
installation.
See "Selection of automation type", paragraph 11.3
Each parameter can still be modified when necessary.
 settings

| AS <br> Type of automa－ tion | Model | CM <br> Motor circuit | R1－R2 <br> Thrust <br> on <br> obsta－ <br> cles and current | VA－VC <br> Speed during opening and closure | VR <br> Learn－ <br> ing speed | $\begin{aligned} & \text { PO-PC } \\ & \text { Ap- } \\ & \text { proach } \\ & \text { speed } \end{aligned}$ | TA <br> Accel－ <br> eration time during opening | TQ <br> Accel－ eration time during closure | VM <br> Ramp start－up speed |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\square 1$ | ОВВІзвн | CL | 50 | 24 | 18 | 07 | 2 | 3 | 03 |
| 号」 | ARCBH |  | 70 | 14 | 10 | 06 | 2 | 3 | 03 |
| ［J | FACIL3H |  | 50 | 12 | 10 | 05 | 2 | 3 | 03 |
| 曻 | LUX03BH－4BH |  | 40 | 16 | 12 | 06 | 1 | 2 | 10 |
| $\square 5$ | LUX05BH－5VBH Igate wing＜ 300 Kg or $3,5 \mathrm{~m}$ ） | OP | 40 | 15 | 10 | 06 | 1 | 2 | 10 |
| ¢ | LUXO5BH－5VBH <br> Igate wing＞ 300 <br> Kg or $3,5 \mathrm{~m}$ ） |  | 50 | 12 | 08 | 05 | 1 | 2 | 10 |
| $\square 7$ | ARC1BH lgate wing＜ 250 Kg \＆ $3 \mathrm{~m})$ | CL | 50 | 08 | 06 | 05 | 2 | 3 | 03 |
| 召口 | ARC1BH Igate wing＞ 250 Kg or $3 \mathrm{~m})$ |  | 60 | 06 | 05 | 04 | 2 | 3 | 03 |
| ¢ | DOR1BH－1BHS <br> Igate wing＜ 300 <br> Kg or $1+1 \mathrm{~m}$ ） |  | 50 | 08 | 06 | 05 | 2 | 4 | 03 |
| 15 | DOR1BH－1BHS <br> lgate wing＞ 300 <br> Kg or $1+1 \mathrm{~m}$ ） |  | 60 | 06 | 05 | 04 | 3 | 6 | 02 |
| 11 | $\begin{aligned} & \text { CUBIC6H-6HV- } \\ & 30 \mathrm{H} \end{aligned}$ |  | 60 | 12 | 08 | 06 | 2 | 3 | 05 |
| 1－ | BOX3SH |  | 50 | 10 | 06 | 05 | 1 | 5 | 03 |
| 13 | DOKE | OP | 50 | 15 | 08 | 05 | 1 | 1 | 03 |
| 14 | PWR25H | CL | 50 | 18 | 10 | 05 | 2 | 3 | 03 |
| 15 | PWR35H |  | 50 | 20 | 12 | 06 | 2 | 3 | 03 |
| 16 | PWR50H Igate wing $<300 \mathrm{Kg}$ or $3,5 \mathrm{~m}$ ） | OP | 40 | 15 | 10 | 06 | 1 | 2 | 10 |
| 17 | PWR50H Igate wing＞ 300 Kg or $3,5 \mathrm{~m}$ ） |  | 50 | 12 | 8 | 05 | 1 | 2 | 10 |
| 18 | PWR40H | CL | 40 | 22 | 15 | 06 | 1 | 2 | 10 |

### 11.3Second level menu - BC (Basic Configurations)

Description
11.3.1 Additional BC level parameters that can be configured lavailable with $\cap T \rightarrow$ 月月 enabled)
Description


### 11.4Second level menu - BA (Basic Adjustment)

Description
It is set with different intervals of sensitivity.

- from $0^{\prime \prime}$ to $59^{\prime \prime}$ with intervals of 1 second
- from $1^{\prime}$ to $2^{\prime}$ with intervals of 10 seconds

|  | Display | Description | Selections available |
| :---: | :---: | :---: | :---: |
|  | $\square$ | R1 - Adjustment of thrust on obstacles and current - motor 1 [\%] <br> The control panel is fitted with a safety device which, when it detects an obstacle: <br> - stops the opening movement and, if outside the limit area for detecting obstacles, performs a disengagement operation whose duration can be set with $A P \rightarrow \cap E$; <br> - reverses the movement during closure operations outside the limit area for detecting obstacles; <br> - stops the movement during closure operations within the limit area for detecting obstacles. <br> The limit area for detecting obstacles during opening and closing is determined by the type of limit switch installed. If there is no limit switch, it is determined on the basis of the selections $B A \rightarrow \square \square$ and $B A \rightarrow \square[$. <br> 00 - Minimum thrust <br> 99 - Maximum thrust | See paragraph 11.2.1 |
|  |  | R2 - Adjustment of thrust on obstacles and current - motor 2 [\%] <br> The control panel is fitted with a safety device which, when it detects an obstacle: <br> - stops the opening movement and, if outside the limit area for detecting obstacles, performs a disengagement operation whose duration can be set with $A P \rightarrow D E$; <br> - reverses the movement during closure operations outside the limit area for detecting obstacles; <br> - stops the movement during closure operations within the limit area for detecting obstacles. <br> The limit area for detecting obstacles during opening and closing is determined by the type of limit switch installed. If there is no limit switch, it is determined on the basis of the selections $\exists R \rightarrow \square \square$ and $B A \rightarrow \square[$. <br> 00 - Minimum thrust <br> 99 - Maximum thrust | See paragraph 11.2.1 |
|  |  | TR - Motor delay time [s] <br> Delay time for closure of gate wing 1 in relation to gate wing 2. $00-30$ s |  |

11.4.1 Additional BA level parameters that can be configured lavailable with $\uparrow T \rightarrow$ คЯ enabled)

TO - Setting motor 2 opening delay time [s]
Adjustment, in seconds, of the delay time for starting the operation of
motor 2, in relation to motor 1 .

|  | Display | Description |
| :---: | :---: | :---: |
| $\frac{1}{0}$ |  | OL - Indicator light for automation open <br> 00 - proportional flashing depending on the point where the gate wings are positioned and the operation direction (in battery mode, the flashing is different) <br> 01 - fixed ON (automation not closed) <br> 02 - output active with automation not open <br> 03 - output active with automation closed <br> 04 - output active with automation open <br> 05 - output active with automation moving <br> 06 - output active with automation opening <br> 07 - output active with automation closing <br> 08 - output active with maintenance alarm triggered <br> 09 - output active for indicating batteries almost flat <br> 10 - Recommended functionality for PWR50HR motor: Connect a relay with 24 V … coil with 250V 16A contact to disconnect the motors when the automation is stopped. Connection diagram in the motor manual. <br> ON - output always active |

NOTE: make adjustments gradually and only after performing at least three complete operations to allow the control panel to be set correctly and detect any friction during operations.

### 11.5 Second level menu - RO (Radio Operations)

Display

You can directly access the Remote control storage menu even with the display turned off, but
only with the Display visualisation mode option set to 00 or 03 :
for transmitting a remote control not present in the memory;
for transmitting an unstored channel of a remote control already present in the memory.

WARNING: selecting MU $\rightarrow$ 2 (200 remote controls), the configurations $U 1$ and $U 己$ saved with the $\bar{\zeta} F \rightarrow \bar{\zeta} b^{\prime}$ command will be lost. This also applies for the last configuration reloaded with PL. In addition, new configurations cannot be saved on $\downarrow \uparrow$ and $\cup$ ?


## 11．5．1Additional RO level parameters that can be configured （available with $口 T \rightarrow$ 月月 enabled）

|  | Display | Description $\begin{gathered}\text { Select } \\ \text { availa }\end{gathered}$ | Selections available |
| :---: | :---: | :---: | :---: |
|  |  | $\mathrm{C} 1, \mathrm{C} 2, \mathrm{C} 3, \mathrm{C} 4$－Selection of $\mathrm{CH} 1, \mathrm{CH} 2, \mathrm{CH} 3, \mathrm{CH} 4$ function of stored remote con－ trol． <br> NO－No setting selected <br> 1－3－Opening command <br> 1－4－Closing command <br> 1－5－Step－by－step command <br> P3－Partial opening command <br> LG－Command to switch the courtesy light on／off <br> 1－9－STOP command <br> If even just one（any）CH key of the remote control is stored，the opening or step－ by－step command is implemented． <br> NOTE：the $1-3$（opening）and $\mid-5$（step－by－step）options are available as alterna－ tives，and depend on the selection $B[\rightarrow R M$ ． <br> If $2-4 \mathrm{CH}$ keys of a single remote control are stored，the functions matched in the factory with the CH keys are as follows： <br> － $\mathrm{CH} 1=$ opening／step－by－step command <br> － $\mathrm{CH} 2=$ partial opening command； <br> －CH3＝courtesy light on／off command <br> － $\mathrm{CH} 4=$ STOP command． | 11 10 $1-$ $1-$ $1-1$ $1-$ $1-$ $1-$ |

Selections
available

### 11.6 Second level menu - SF (Special Functions)

Description
Display

## 11．6．1Additional SF level parameters that can be configured lavailable with $口 T \rightarrow$ 月月 enabled）

Sisplay
Respription

### 11.7 Second level menu - CC (Cycles Counter)

Display

### 11.7.1 Additional CC level parameters that can be configured (available with $口 T \rightarrow$ คЯ enabled)



### 11.8 Second level menu - EM (Energy Management)



### 11.8.1 Additional EM level parameters that can be configured (available with $Я T \rightarrow$ คЯ enabled)



### 11.9 Second level menu - AP (Advanced Parameters)


 operations to allow the control panel to be set correctly and detect any friction during operations.
11.9.1 Additional AP level parameters that can be configured lavailable with $Я T \rightarrow$ ЯЯ enabled)
Description
LU - Setting the courtesy light switch-on time (s)
To enable this parameter, set at least one of the selections BR
or BR $\rightarrow F F$ as a courtesy light.
It is set with different intervals of sensitivity.
NO - Disabled

- from 01" to 59 " with intervals of 1 second
- from 1' to 2' with intervals of 10 seconds
- from 2 to 3 with intervals of 1 minute
ON - Permanently enabled (switched off via remote control)
NOTE: the courtesy light switches on at the start of each operation.
NO
Description
OT - Selection of type of obstacle
01 - Overcurrent or gate stopped
02 - Door stopped

| 0 | Display | Description | Selections available |
| :---: | :---: | :---: | :---: |
|  | IV I | WC - Setting of pre-flashing time on closing [s] <br> Adjustment of the lead time for the switch-on of the flashing light, in relation to the start of the closing operation from a voluntary command. <br> 00 - Minimum <br> 05 - Maximum |  |
|  | $1]$ | TS - Setting of renewal of automatic closing time after safety device release [\%] <br> 00 - Minimum <br> 99 - Maximum |  |
| $\frac{1}{4}$ | $1, m$ | VR - Setting of learning speed [V] | See paragraph 11.2.1 |

## 12. Diagnostics

### 12.1 Data Logging integrated in the board

The Ditec LCU40H control panel is equipped with an internal system that allows the installer to check whether any alarms have been triggered, how many times, and the log of the last twenty alarms.

### 12.1.1 Alarm counter

With the third level menus enabled $(A T \rightarrow A R)$, go to $\bar{\zeta} F \rightarrow A L$ to see all the alarms recorded by the control panel. The display alternately shows the alarm code and the number of times it was triggered.

Use the $\triangle \Delta$ and keys to scroll through the entire list of alarm counters.

### 12.1.2 Alarm log

With the third level menus enabled ( $A T \rightarrow$ AR), go to $\overline{5} F \rightarrow$ AH to see the alarm log (the last 20 alarms recorded). The display shows the alarm number and code, alternated. The highest number corresponds to the most recent alarm and the lowest number corresponds to the oldest alarm.

Use $\triangle \Delta$ and $\square$ to scroll through the alarm log.

### 12.1.3 Exporting information on the microSD

With the third level menus enabled ( $A T \rightarrow$ RA), the microSD card inserted and the automation idle, go to $\overline{5} F \rightarrow$ RE to export all the control panel parameters to the microSD. The LCU4OH_INFO.txt text file created on the microSD contains all the alarm counters, the log showing the last twenty alarms, the operating statistics and the complete configuration of the control panel.
By inserting the microSD in a PC and opening the file LCU4OH_INFO.txt with the Ditec software, you can view all the control panel data.

iNOTE: when the installation is complete, you are advised to delete the internal data logging.

### 12.2 Extended data logging on microSD

The Ditec LCU40H control panel can record every event and/or alarm for every operation performed.
To do this, you must leave a microSD inserted in the relative connector and then, with the third level menus enabled ( $A T \rightarrow$ RR), set $\bar{\zeta} F \rightarrow E \mathbb{B} \rightarrow 0$.
In this way, at the end of every operation the control panel will save all the events recorded up to that moment on the microSD (in the LCU40H.log file in the LCU40H_ LOG folder).
You can view all the recorded logs by inserting the microSD in a PC and opening the LCU40H.log file using the Ditec software.
This is an example of the visualisation of recorded events:


## 13. Signals visualised on the display

NOTE: depending on the type of automation and control panel, certain visualisations may not be available.

### 13.1 Display of automation status

> NOTE: the automation status display mode is only visible with Display visualisation mode set to 02 .


### 13.2 Display of safety devices and commands

iNOTE: the safety device and command visualisation mode is only visible with Display visualisation mode set at 01 or 03 .


| Display | Description |
| :--- | :--- |
| $1-2$ - Automatic closing activation com- |  |
| and |  |



| Display | Description |
| :---: | :---: |
| $\square]$ | P3 - Partial opening command |
| $30$ | 3P - Opening command with operator present |
| -15 | 4 P - Closing command with operator present |
|  | RX - Radio reception lof any memorised key of a transmitter present in the memory) |
| ivy | NX - Radio reception lof any non-memorised key) <br> NOTE: with the selection $\mathrm{AP} \rightarrow$ П $\overline{5} \rightarrow$ 1. it is also visualised when a command is received from a non-stored transmitter. |
| E M | EX - Rolling-code radio reception out of sequence |
| $[\square$ | EP - Radio reception not complying with the parameter configuration $R \square \rightarrow$ EP |
| [ | CX - Command received from AUX1 board |
| L | CY - Command received from AUX2 board |
| $F E$ | FC. - Closure limit switch - motor 1 |
| F.L | F.C. - Closure limit switch - motor 2 |
| $F \square$ | FA. - Opening limit switch - motor 1 |
| F.F. | F.A. - Opening limit switch - motor 2 |
| $\text { F } 1$ | S1. - Detection of stop during closure motor 1 |
| -1. | S.1. - Detection of stop during closure motor 2 |

Description
Display
R2. - Detection of stop during opening -
motor 1

### 13.3 Visualisation of alarms and faults

WARNING: the visualisation of alarms and faults is possible with any visualisation selection. The signalling of alarm messages takes priority over all other displays.

Thpe of | Description |
| :--- |
| alarm |

Type of
alarm

| Type of alarm | Display | Description | Operation |
| :---: | :---: | :---: | :---: |
|  | $91$ | RO - Insertion of a storage module containing over 100 stored remote controls WARNING: the RD $\rightarrow M \cup \rightarrow 2 \square$ setting is made automatically. | To save the system configurations on the storage module, delete any stored remote controls and bring the total to less than 100. Set R $\mathrm{P} \rightarrow \mathrm{MU} \rightarrow$ 10. |
|  |  | R3 - Storage module not detected | Insert a storage module. |
|  | $4$ | R4 - Storage module not compatible with the control panel | Insert a compatible storage module. |
|  | $-$ | R5 - No serial communication with the storage module | Replace the storage module. |
|  |  | R6 - Insertion of a specific storage module for testing |  |
|  |  | P0 - No mains voltage | Check the control panel is powered cor rectly. <br> Check the line fuse. <br> Check the mains power supply. |
|  | $1$ | P1-Microswitch voltage too low | Check the control panel is powered correctly. |
|  | $\begin{aligned} & 11 \\ & 11 \end{aligned}$ | B0 - Battery almost flat | Check battery voltage. Replace battery. |
|  |  | A0 - Failure of test of safety sensor on contact 6 | Check the device SOFA1-A2 is working correctly. <br> If the supplementary SOF board is not inserted, check the safety test is disabled. |
|  |  | A1 - Simultaneous safety sensor test on contacts 6 and 8 failed | Check the wiring and correct operation of the safety sensor. |
|  | 〕1 | A3 - Failure of test of safety sensor on contact 8 | Check the device SOFA1-A2 is working cor rectly. <br> If the supplementary SOF board is not inserted, check the safety test is disabled. |
|  |  | A7 - Incorrect connection of contact 9 to terminal 41 | Check that terminal 1 and 9 are correctly connected. |
|  |  | A9 - Overload on output +LP- | Check the device connected to output +LP - is working properly. |
|  | $11$ | AB - Overload on output 30-13 | Check the device connected to output 30-13 is working properly. |
|  |  | AG - Alarm for short-circuit on output - LK+ | Check the device connected to output -LK+ is working properly. |

## 14．Troubleshooting

| Problem | Possible cause | Alarm sig－ nalling | Operation |
| :---: | :---: | :---: | :---: |
| The control panel does not switch on | No power supply． |  | Check the power supply cable and the relative wiring |
|  | Overload on output 0－30 |  | Disconnect any loads connected to ter－ minal 30 |
| The automation does not open or close． | No power． |  | Check power supply cable． |
|  | Short－circuited accessories | 15 | Disconnect all accessories from ter－ minals $0-30$ la voltage of $24 \mathrm{~V}=$ must be present），then reconnect them one at a time． <br> Contact Technical Service |
|  | Blown line fuse． |  | Replace fuse． |
|  | Safety contacts are open． | $\begin{array}{l\|l} 1-6 & 1-日 \\ 5 日 & \end{array}$ | Check that the safety contacts are closed correctly（NC）． |
|  | Safety contacts not correctly connected or self－controlled safety edge not functioning correctly． | RO $1-G$ <br> $R 1$ $1-\theta$ <br> R 3 $6 日$ | Check connections to terminals 6－8 on control panel and connections to the self－controlled safety edge． |
|  | Photocells activated． | 1－6 1－8 | Check that the photocells are clean and operating correctly． |
|  | The automatic closure does not work． |  | Issue any command．If the problem per－ sists，contact Technical Service |
|  | Motor fault | $\begin{aligned} & M B \\ & M[ \end{aligned}$ | Check motor connection，if the problem persists，contact Technical Service． |
| The external safety devices are not ac－ tivated． | Incorrect connections be－ tween the photocells and the control panel． |  | Check that $1-5 / 1-8$ is displayed Connect NC safety contacts together in series and remove any jumpers on the control panel terminal board． |
|  |  |  | Check the AP $\rightarrow$ IE and RP $\rightarrow$昍 setting |
| The automation opens／closes briefly and then stops． | There is a presence of friction． | MI | Manually check that the automation moves freely and check the R $1 / R_{\mathrm{R}}$ 己 adjustment． <br> Make sure that any limit switches，if present，are working correctly． Contact Technical Service |
| The remote control has limited range and does not work with the auto－ mation moving． | The radio transmission is im－ peded by metal structures and reinforced concrete walls． |  | Install the antenna outside． |
|  |  |  | Replace the transmitter batteries． |
| The remote control does not work | No storage module or incor－ rect storage module． | $\begin{aligned} & R \square \\ & R 3 \\ & R 5 \end{aligned}$ | Switch the automation off and plug in the correct storage module． |
|  |  |  | Check the correct memorisation of the transmitters on the built－in radio．If there is a fault with the radio receiver that is built into the control panel，the remote control codes can be read by removing the storage module． |

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